

FATEK®

FBS-series Programmable Controller


User's Manual - II

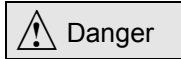
[Advanced Application]

Preface, Contents

FBs-PLC Interrupt Function	9
FBs-PLC High-Speed Counter and Timer	10
Communication of FBs-PLC	11
The Applications of FBs-PLC Communication Link	12
The NC Position Control of FBs-PLC	13
Application of ASCII Output Function	14
Real Time Clock (RTC)	15
FBs-7SG 7/16-Segment LED Display Module	16
FBs-32DGI Thumbwheel Switch Input Module	17
FBs-6AD Analog Input Module	18
FBs-4DA/2DA Analog Output Module	19
FBs-4A2D Analog Input/Output Module	20
Temperature Measurement of FBs-PLC and PID Control	21
General Purpose PID Control	22
Instruction List of FBs-PLC	Appendix 1
FATEK Communication Protocol	Appendix 2
FBs-PACK Operation Instruction	Appendix 3

Attention related to safety (Read carefully before application)

⊙ For the purpose of ensuring your personal safety and protecting this product and its peripheral equipment, read this manual regarding the safety functions carefully before installation and operation of the FBs PLC. The three safety categories of this manual are classified into 「Danger」, 「Warning」, 「Caution」 grade according to the danger level and are preceded by the “” symbol. Following is their description:



Indicates casualty or serious damage or property loss will result if the correct instruction was not followed.



Casualty or serious damage or property loss may result if the correct instruction was not followed.



Indicates minor damage or property loss will result if the correct instruction was not followed.

⊙ This manual is a guideline for qualified personnel on how to install the FBs PLC correctly and use it safely. The qualified personnel stated here means professional electromechanical engineering personnel who is familiar with safety specifications and methods of grounding, circuit wiring, peripheral equipment system etc. and possesses practical experience.

Danger

⊙ Keep in mind before using the PLC

Abnormality in the external power supply or failure of the PLC itself will result in the PLC or the complete system emerging in an unsafe status, and may cause unpredictable actions. Such actions may cause human injury, death, or serious damage of the unit itself. Thus, please design a separate external safety protection circuit, such as emergency stop circuit, machine replacement device, or redundant safety protection circuit in your application with the following safety considerations:

1. Emergency stop circuit, safety protection circuit, motor positive/reverse interlock circuit, upper/lower limit destruction prevention circuit of position control, etc. These circuits should be hardwired and external to the PLC.
2. The PLC is unable to detect the abnormality of the input signal circuit (such as overload or interrupted PLC input circuit. The PLC interprets them as OFF, then erroneous output may result in the PLC and may cause major safety problems, thus external detection and protection circuits should be provided in addition to the PLC.
3. The output components of the PLC, whether relay, transistor, or TRIAC are possible to cause permanent ON or OFF and resulting in serious accidents, thus protection by additional external circuits or mechanisms is necessary for the output points to avoid major safety problems.

PREFACE

It has been more than ten years since FATEK Automation Corporation first introduced its FB series PLC in 1993. Since then, to maintain a leading edge in functionality of the FB-PLC, there have been two major revamps in redesigning the ASIC(Application specific IC), while keeping the function and dimension downward compatible. Though the revenue of our FB-PLC is still keep growing and remains superior in quality, functionality and competitiveness to our rivals, shrinking the dimension of the FB-PLC is still a common request when compared with other brands of PLC. In light of the need to design a compact yet highly functional micro PLC, the FBs series was launched by FATEK as a all-new series of micro PLC designed and developed to better serve the market demand for the next decade.

To maintain a competitive edge in the next decade, the design of the function specifications of FBs-PLC have greatly exceeded a lot of micro PLC presently sold in the market. For instance, it comes with many advanced hardware functions, including five communication ports with the speed up to 921.6 Kpbs, four sets of hardware high-speed counters with counting frequency up to 920 KHz, four sets of high-speed pulse outputs with linear interpolation function and output frequency can up to 920 KHz, four sets high-speed PWM(Pulse width modulation) output with 184.32KHz max. output frequency, and five sets of 0.1ms time-base high-speed counters. In the meantime, to strengthen cost competitiveness, the FATEK have developed a SoC(System on a chip) for FBs-PLC that integrates all peripherals and CPU into a single chip. This cuts down the physical bulk and reduces costs, as well as improves its reliability, allowing the compact FBs-PLC to provide the functions incomparable by medium- to large-size PLC, and excels the user of FBs-PLC to outrun its peers.

The FBs-PLC's instruction set not only contains additional newly high-end functional instructions, but it is also fully compatible with the previous FB series PLC. When compared with the earlier generation of FB series PLC, the new FBs-PLC not only possess greatly improved communication functions, totaling 14 communication boards and communication modules for user's option, but there is also an added USB interface in addition to the existing RS-232, RS-485 and Ethernet. In I/O module, besides the previous FB-PLC's modules, there has been an added 16-segment (alphanumeric) display module, thumbwheel switch multiplex input module, A/D and D/A combo modules and so forth. The temperature module has been revamped to a general structure, with a built-in CPU, allowing it to connect various temperature sensor such as J, K, R, S, E, T, B, and N thermocouples or pt-100, pt-1000's RTD.

The FBs-PLC's user manual comes in two volumes. Volume I covers the basic topics regarding the hardware and Instruction Set, while Volume II covers the advanced topics about the special modules and their application. The 'Hardware' part of Volume I present an introduction to the FBs-PLC's hardware framework, covering the mechanism, installation, power, I/O and safety compliance description. The 'Instruction Set' part of Volume I describes the FBs-PLC's instruction category and their functionality. The Volume II focuses on advanced applications, such as communication, networking, interrupt, high-speed counting, NC positioning output, temperature PID, multiplex input/output and so forth, together with simplified illustrations and application descriptions.

FBs-PLC User's Manual II 【Advanced Application】

CONTENTS

Chapter 9 FBs-PLC Interrupt Function

9.1	The principle and the structure of interrupt function	9-1
9.2	Structure and application of interrupt service routine	9-2
9.3	Interrupt source, label and priority for FBs-PLC	9-3
9.4	How to use interrupt of FBs-PLC	9-5
9.5	Interrupt configuration	9-5
9.5.1	Interrupt configuration through the operation of WinProladder	9-6
9.5.2	Interrupt configuration through the operation of FP-07C	9-7
9.5.3	Internal time base Interrupt configuration by R4162	9-8
9.6	Examples of interrupt routine	9-8
9.7	Captured input and digital filter	9-10

Chapter 10 FBs-PLC High-Speed Counter and Timer

10.1	FBs-PLC high-speed counter	10-1
10.1.1	Counting modes of FBs-PLC high-speed counter	10-1
10.2	System architecture of FBs-PLC high-speed counter	10-2
10.2.1	The up/down pulse input mode of high-speed counter (MD0,MD1)	10-4
10.2.2	Pulse/direction input mode of high-speed counter (MD2, MD3)	10-6
10.2.3	AB phase input mode of high-speed counter (MD4,MD5,MD6,MD7)	10-7
10.3	Procedures for FBs-PLC high-speed counter application	10-10
10.4	HSC/HST configuration	10-10
10.4.1	HSC/HST configuration (Using WinProladder)	10-10
10.4.2	HSC/HST configuration (Using FP-07C)	10-12
10.5	Examples for application of high-speed counter	10-16
10.6	FBs-PLC high-speed timer	10-21
10.6.1	HSTA high-speed timer	10-21
10.6.2	HST0~HST3 high-speed delay timers	10-24
10.6.3	Examples for application of high-speed timer HSTA	10-25
10.6.4	Examples for application of high-speed timer HST0~HST3	10-29

Chapter 11 The Communication Function of FBs-PLC

11.1	Functions and applications of FBs-PLC communication ports	11-1
11.1.1	Communication port 0 : USB or RS232 interface	11-2
11.1.2	Communication port 1~4 : RS232 or RS485 interface	11-2
11.1.3	Ethernet interface	11-3
11.2	How to use FBs-PLC communication functions	11-4
11.3	Hardware wiring notifications for RS485 interface	11-4
11.4	How to use FBs-PLC communication ports	11-8
11.4.1	Matching of hardware interfaces and mechanisms	11-8
11.4.2	Selection and setting of communication protocols	11-11
11.4.3	Settings for communication parameters	11-13
11.4.4	Modem interface setting	11-17
11.5	Description and application of software interface type	11-18
11.5.1	Standard interface	11-18
11.5.2	Modem-specific interface	11-18
11.5.3	Ladder program control interface	11-20
11.6	Communication boards (CB)	11-21
11.7	Communication modules (CM)	11-23
11.7.1	4-port RS485 central hub (FBs-CM5H)	11-25
11.7.2	Isolated RS485 repeater (FBs-CM5R)	11-27
11.7.3	Isolated RS232/RS485 converter (FBs-CM25C)	11-27
11.8	FBs Ethernet communication module and application	11-28
11.8.1	Specifications	11-28
11.8.1.1	Connector specifications	11-28
11.8.1.2	Ethernet specifications	11-28
11.8.2	Appearance	11-29
11.8.2.1	CM25E and CM55E appearance	11-29
11.8.2.2	CBE appearance	11-30
11.8.3	Serial connector function	11-31
11.8.4	The function of Ethernet serial converter	11-31
11.8.5	Application architecture	11-31
11.8.5.1	Server mode	11-32

11.8.5.2 Client mode.....	11-33
11.8.6 Hardware installation.....	11-34
11.8.7 Software setup	11-35
11.8.8 Procedures to change the configuration	11-41
11.8.9 Pin assignment and protocols.....	11-42

Chapter 12 The Applications of FBs-PLC Communication Link

12.1 Application for FUN151 (CLINK) instruction.....	12-2
12.1.1 Procedures for usage.....	12-2
12.1.2 Explanation of respective modes and application program for FUN151	12-2
12.2 Application for FUN150 (ModBus) instruction.....	12-33
12.2.1 Procedures for usage.....	12-33
12.2.2 Explanation application program for FUN150.....	12-33

Chapter 13 The NC Positioning Control of FBs-PLC

13.1 The methods of NC positioning.....	13-1
13.2 Absolute coordinate and relative coordinate	13-1
13.3 Procedures of using FBs-PLC positioning control.....	13-2
13.4 Explanation for the positioning control	13-3
13.4.1 Structure of output circuit of HSPSO	13-3
13.4.2 Hardware wiring layout for FBs-PLC positioning control	13-3
13.5 The explanation for the positioning control function of FBs-PLC.....	13-5
13.5.1 Interface of stepping motor	13-6
13.5.2 Interface of servo motor.....	13-7
13.5.3 Working diagram illustration for servo motor	13-8
13.6 Explanation of function for NC positioning control instruction	13-8
13.7 Machine homing.....	13-27

Chapter 14 Application Of ASCII File Output Function

14.1 Format of ASCII file.....	14-1
14.2 Application examples of ASCII file output.....	14-3

Chapter 15 Real Time Clock (RTC)

15.1 Correspondence between RTC and the RTCR within PLC	15-1
15.2 RTC access and setting.....	15-2

Chapter 16 FBs-7SG 7/16-Segment LED Display Module

16.1	FBs-7SG overview	16-1
16.2	The procedures of using FBs-7SG module	16-2
16.3	FBs-7SG I/O address	16-2
16.4	FBs-7SG hardware wiring and setup	16-2
16.4.1	FBs-7SG hardware wiring	16-2
16.4.2	FBs-7SG hardware setup	16-3
16.4.3	LED driving voltage setup and over-voltage(O.V.) inspection	16-6
16.5	7-segment LED display and individual LED display circuits	16-7
16.6	Decode display and Non-decode display	16-9
16.7	FBs-7SG input power requirements and consumption	16-12
16.8	Controlling display contents with OR on FBs-7SG	16-12
16.9	FBs-7SG output commands FUN84:TDSP	16-13

Chapter 17 FBs-32DGI Digital Switch Input Module

17.1	FBs-32DGI specifications	17-2
17.2	The procedure of using FBs-32DGI module	17-2
17.3	FBs-32DGI I/O address	17-3
17.4	FBs-32DGI hardware description	17-3
17.5	FBs-32DGI input circuit diagram	17-5

Chapter 18 FBs-6AD Analog Input Module

18.1	Specifications of FBs-6AD	18-1
18.2	The procedure of using FBs-6AD module	18-2
18.3	Address allocation of FBs-PLC analog inputs	18-2
18.4	FBs-6AD hardware description	18-3
18.4.1	FBs-6AD hardware Jumper setting	18-4
18.5	FBs-6AD input circuit diagram	18-7
18.6	FBs-6AD input characteristics and jumper setting	18-7
18.7	Configuration of analog input	18-12
18.8	Tacking on the offset mode input	18-15

Chapter 19 FBs-4DA/2DA Analog Output Module

19.1	Specifications of FBs-4DA/2DA	19-1
19.2	The procedures of using FBs-4DA/2DA analog output module	19-1
19.3	Address allocation of FBs-PLC analog outputs	19-2
19.4	FBs-4DA/2DA hardware description	19-3
19.4.1	FBs-4DA/2DA hardware jumper setting	19-4
19.5	FBs-4DA/2DA output circuit diagram	19-6
19.6	FBs-4DA/2DA output characteristics and jumper setting	19-7

Chapter 20 FBs-4A2D Analog Input/Output Module

20.1	Specifications of FBs-4A2D	20-1
20.2	The procedures of using FBs-4A2D analog input/output module	20-2
20.3	Address allocation of FBs-PLC analog inputs/outputs	20-3
20.4	FBs-4A2D hardware description	20-4
20.4.1	FBs-4A2D hardware jumper setting	20-5
20.5	FBs-4A/2D input/output circuit diagram	20-8
20.6	FBs-4A2D input/output characteristics	20-8
20.7	FBs-4A2D analog input format planning	20-13

Chapter 21 Temperature Measurement and PID Control of FBs-PLC

21.1	Specifications of temperature modules of FBs-PLC	21-1
21.1.1	Thermocouple input of FBs-PLC	21-1
21.1.2	RTD input of FBs-PLC	21-2
21.2	The procedures of using FBs temperature module	21-2
21.2.1	Temperature measurement procedure	21-2
21.2.2	Closed loop PID temperature control	21-3
21.3	The procedures to configure the temperature measurement	21-3
21.3.1	The internal format of temperature configuration table	21-4
21.3.2	The internal format of working registers	21-5
21.3.3	Description of related special registers for temperature measurement	21-6
21.4	I/O address of the temperature module	21-6
21.5	Temperature modules hardware description	21-6
21.5.1	FBs-TC2/TC6/TC16 outlook of top view	21-6

21.5.2	FBs-RTD6/RTD16 outlook of top view	21-9
21.6	Wiring of the temperature modules	21-10
21.6.1	Wiring of the thermocouple input module	21-10
21.6.2	Wiring of the RTD input module	21-11
21.7	Instructions explanation and program example for temperature measurement and PID control of FBs-PLC	21-11

Chapter 22 General purpose PID control

22.1	Introduction of PID control	22-1
22.2	How to select the controller	22-1
22.2.1	Proportional controller	22-2
22.2.2	Proportional + Integral controller	22-2
22.2.3	Proportional + Integral + Derivative controller	22-2
22.3	Explanation of the PID Instruction and example program follows	22-3

【Appendix 1】 Instruction List of FBs-PLC

●	General Timer/Counter Instructions	-1
●	Single Operand Instructions	-1
●	SET/RESET Instructions	-1
●	SFC Instructions	-1
●	Mathematical Operation Instructions	-1
●	Logical Operation Instructions	-3
●	Comparison Instructions	-3
●	Data Movement Instructions	-3
●	Shifting/Rotating Instructions	-4
●	Code Conversion Instruction	-4
●	Flow Control Instructions	-5
●	I/O Instructions	-5
●	Cumulative Timer Instructions	-6
●	Watch Dog Timer Control Instructions	-6
●	High Speed Counter Instructions	-6
●	Report Instructions	-6
●	Ramp Instructions	-6
●	Communication Instructions	-6

- Table Instructions-7
- Matrix Instructions.....-7
- NC Positioning Instruction-8
- Disable/Enable Control of Interrupt or Peripheral.....-8

【Appendix 2】 FATEK Communication Protocol

1. Master and Slave definition and communication.....-1
2. The communication message format of FATEK PLC.....-1
3. The communication error code of FATEK PLC-2
4. The function description of communication command-3
 - 4.1 The classification and assignment of components-3
 - 4.2 The description of communication command-4
 - command 40: Read the system status of PLC-6
 - command 41: Control the PLC RUN/STOP.....-7
 - command 42: Single discrete control-8
 - command 43: The status reading of ENABLE/DISABLE of continuous discrete.....-9
 - command 44: The status reading of continuous discrete-10
 - command 45: Write the status to continuous discrete-11
 - command 46: Read the data from continuous registers.....-12
 - command 47: Write to continuous registers-13
 - command 48: Mixed read the random discrete status or register data-14
 - command 49: Mixed write the random discrete status or register data-15
 - command 4E: Loop back testing-16
 - command 53: Read the detailed system status of PLC.....-17

【Appendix 3】 FBs-PACK Operation Instruction

- 1.1 Write program and register data to FBs-PACK through WinProladder-1
- 1.2 Write program and register data to FBs-PACK through special register operation-3
- 1.3 Assigning the retrieval of register stored FBs-PACK-5
- 1.4 Read and write FBs-PACK by function instruction-6